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MIXED CONVECTION FLOW BY A POROUS SHEET WITH VARIABLE THERMAL CONDUCTIVITY AND CONVECTIVE BOUNDARY CONDITION

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Abstract - Effects of variable thermal conductivity on the mixed convection flow over a porous stretching surface are investigated. Analysis has been performed subject to the convective boundary conditions. The fluid is electrically conducting in the presence of a uniform applied magnetic field. The resulting problems are computed. The effects of emerging parameters on the velocity and temperature profiles are displayed and discussed. The values of the skin-friction coefficient and local Nusselt number are analyzed numerically. *Keywords*: MHD flow; Variable thermal conductivity; Convective boundary condition.

INTRODUCTION

Stretching flow is an important topic of research undergoing rapid growth amongst the recent investigators. Such interest of researchers is due to the broad range of practical applications of such flows in engineering, including extrusion processes, glass fibers and paper production, drawing of plastic films, crystal growing and many others. Stretched flows have been extensively analyzed since the seminal work of Sakiadis (1961) in view of diverse aspects including heat and mass transfer, MHD, suction/injection, non-Newtonian fluids, similar and non-similar solutions etc. For example, Kechil and Hashim (2009) addressed the MHD stagnation point flow of viscous fluid in a porous medium. The Adomian decomposition method was utilized for the expressions of velocity and temperature. Thermal radiation effects in unsteady magnetohydrodynamic (MHD) flow have been discussed by Hayat and Qasim (2010). Here the series solutions are computed by the homotopy analysis method. Ishak (2010) carried out a study for the radiation effects in boundary layer flow of a micropolar fluid. Newtonian heating effects in the boundary layer flow of a viscous fluid with heat transfer were studied by Salleh et al. (2010). Tsai and Haung (2009) investigated the Soret and Dufour effects in natural convection flow of a viscous fluid with variable heat flux. Numerical solutions were given for the velocity, temperature and concentration. Exact solutions of viscous fluid flow over a stretching surface with slip condition were presented by Fang et al. (2009). Bhattacharyya and Layek (2011) discussed the effects of suction/ blowing on the boundary layer stagnation point flow in the presence of heat transfer and thermal radiation. Havat and Oasim (2010) analyzed the Joule heating and thermophoresis effects in the MHD flow of a Maxwell fluid with radiation. Falkner-Skan flow of a viscous fluid with stretching boundary was presented by Yao (2009). It is revealed from the previous literature that most of the works undertaken works

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were performed without considering the convective boundary conditions. Few authors take into account such boundary conditions. For example, Aziz (2009) analyzed the impact of convective type boundary conditions on the boundary layer flow of a viscous fluid over a flat plate. Yao et al. (2011) investigated the heat transfer analysis in a viscous fluid over a stretching/shrinking sheet with convective boundary conditions. Ishak (2011) also studied the flow problem with convective boundary conditions. All these studies have been restricted to the situations of constant thermal conductivity. Chiam (1998) examined the effects of variable thermal conductivity on the boundary layer flow of a viscous fluid over a stretching sheet. Chiam (1996) also discussed the stagnation point flow of a viscous fluid towards a stretching sheet in the presence of variable thermal conductivity. Sharma and Singh (2008) investigated the viscous flow and heat transfer with variable thermal conductivity.

However, no attempt has yet been presented for the effect of variable thermal conductivity on the flow due to a stretched sheet with convective boundary conditions. Such a concept is important in the sense that thermal conductivity for liquid metals varies with temperature in a linear manner in the range of $0^0 F$ to $400^0 F$ (Vyas and Rai, 2010). Hence, the aim of the present study is to investigate the MHD mixed convection flow over a stretching surface with convective boundary conditions when the thermal conductivity of the fluid is variable. The homotopy analysis method (HAM) was applied to find the series solutions of the problem (Liao, 2003, 2004; Abbasbandy and Shivanian, 2010, 2011; Hashim et al., 2009; Hayat et al., 2010, 2011, 2012). The solutions developed are displayed and discussed.

PROBLEM STATEMENT

Here we choose the Cartesian coordinate system in such a manner that the x-axis is along the stretched sheet and the y-axis is normal to it. We consider the MHD mixed convection flow of a viscous fluid with convective boundary conditions over a porous stretching sheet. All the physical properties of the fluid except the thermal conductivity are taken to be constant. The thermal conductivity varies linearly with the temperature. Neglecting the radiative and viscous dissipation effects, the boundary layer equations are:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0, \tag{1}$$

$$u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} = v\frac{\partial^2 u}{\partial y^2} + g\beta_T (T - T_\infty) - \frac{\sigma B_0^2}{\rho}u, \qquad (2)$$

$$\rho C_p \left(u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} \right) = \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right), \tag{3}$$

with the boundary conditions:

$$u = u_w(x) = cx, \ v = v_w,$$

$$-k \frac{\partial T}{\partial y} = h(T_f - T) \text{ at } y = 0,$$
(4)

$$u \to 0, \quad T \to T_{\infty} \quad \text{as } y \to \infty.$$
 (5)

Note that the temperature boundary condition in Eq. (4) indicates that the bottom surface of the sheet is heated by convection from a hot fluid at temperature T_f , providing a heat transfer coefficient *h*. In the above equations *u* and *v* are the velocity components parallel to the x- and y- axes respectively, v the kinematic viscosity, β_T the thermal expansion coefficient, *T* the temperature, *k* the variable thermal conductivity, ρ the density of the fluid, C_p the specific heat at constant pressure and *c* the rate of stretching. The magnetic Reynolds number is chosen small and thus the induced magnetic field is neglected.

We introduce the following variables (Yao *et al.*, 2011):

$$u = cxf'(\eta), \ v = -\sqrt{cv} f(\eta), \ \eta = y\sqrt{\frac{c}{v}},$$

$$\theta(\eta) = \frac{T - T_{\infty}}{T_f - T_{\infty}}$$
(6)

where *c* is a constant, prime denotes the differentiation with respect to η and we consider $T_w(x) = T_{\infty} + Dx^{\alpha^*} \theta(\eta)$ at $\eta = 0$ and variable thermal conductivity $k = k_{\infty}[1 + \varepsilon \theta]$, k_{∞} is the fluid free stream conductivity and ε is defined as:

$$\varepsilon = \frac{(k_w - k_\infty)}{k_\infty}.$$
(7)

The transformations in Eq. (6) satisfy the incompressibility condition and now Eqs. (2) - (5) give:

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(11)

$$f''' + ff'' - f'^{2} + \lambda \theta - M^{2} f' = 0,$$
(8)

$$(1+\varepsilon\theta)\theta''+\varepsilon\theta'^2 = \Pr[\alpha^*\theta f' - f\theta'], \qquad (9)$$

$$f = S, f' = b / c = \alpha, \theta' = -\gamma(1 - \theta(0))$$

at $\eta = 0,$ (10)

$$f' = 0, \ \theta = 0 \ \text{as } \eta \to \infty,$$

in which $\lambda = \frac{Gr_x}{\text{Re}_x^{1/2}}$ where $Gr_x = g\beta(T_f - T_\infty)x^3 / v^2$ is the local Grashoff number and $\text{Re}_x = u_w x / v$ is the local Reynolds number, $M^2 = \frac{\sigma B_0^2}{\rho c}$ is the Hartman number, $\gamma = \frac{h}{k} \sqrt{\frac{v}{c}}$ is the Biot number and $\text{Pr} = \frac{\rho C \rho v}{k_\infty}$ is the Prandtl number.

The skin-friction coefficient C_f and local Nusselt number Nu_x are defined as

$$C_f = \frac{\tau_w}{\rho U_w^2 / 2}, \quad Nu_x = \frac{xq_w}{k(T_f - T_\infty)},$$
 (12)

in which τ_w and q_w are given by:

$$\tau_w = \mu \left(\frac{\partial u}{\partial y}\right)_{y=0}, \ q_w = -k \left(\frac{\partial T}{\partial y}\right)_{y=0}.$$
 (13)

On a dimensionless scale, Eq. (12) becomes:

$$\frac{1}{2}C_f \operatorname{Re}_x^{1/2} = f''(0), \ Nu / \operatorname{Re}_x^{1/2} = -\theta'(0).$$
(14)

SOLUTIONS EMPLOYING HAM

We express f and θ in the set of base functions:

$$\{\eta^k \exp(-n\eta)k \ge 0, n \ge 0\},\tag{15}$$

as follows

$$f(\eta) = a_{0,0}^0 + \sum_{n=0}^{\infty} \sum_{k=0}^{\infty} a_{m,n}^k \eta^k \exp(-n\eta),$$
(16)

$$\theta(\eta) = \sum_{n=0}^{\infty} \sum_{k=0}^{\infty} b_{m,n}^{k} \eta^{k} \exp(-n\eta), \qquad (17)$$

in which $a_{m,n}^k$ and $b_{m,n}^k$ are the coefficients.

The initial approximations and auxiliary linear operators are given below:

$$f_0(\eta) = 1 - \exp(-\eta), \ \theta_0(\eta) = \exp(-\eta),$$
 (18)

$$L_f = f''' - f', \quad L_\theta = \theta'' - \theta, \tag{19}$$

with:

$$L_{f}(C_{1} + C_{2}e^{\eta} + C_{3}e^{-\eta}) = 0,$$

$$L_{\theta}(C_{4}e^{\eta} + C_{5}e^{-\eta}) = 0,$$
(20)

where C_i (i = 1-5) denote the arbitrary constants. The following problems corresponding to the zeroth order deformations are constructed:

$$(1-q)L_{f}\left[\hat{f}(\eta;q)-f_{0}(\eta)\right] =$$

$$p\hbar_{f}\mathbf{N}_{f}\left[\hat{f}(\eta;q),\hat{\theta}(\eta;q)\right],$$
(21)

$$(1-q)L_{\theta}\left[\hat{\theta}(\eta;q) - \theta_{0}(\eta)\right]$$

= $p\hbar_{\theta}\mathbf{N}_{\theta}\left[\hat{f}(\eta;q), \hat{\theta}(\eta,q)\right],$ (22)

$$\hat{f}(0;q) = S, \ \hat{f}'(0;q) = 1, \ \hat{f}'(\infty;q) = 0,$$

$$\hat{\theta}'(0;q) = -\gamma(1 - \theta(0;q), \ \hat{\theta}'(\infty,q) = 0,$$
(23)

$$\mathbf{N}_{f}[\hat{f}(\eta,q)] = \frac{\partial^{3}\hat{f}(\eta,q)}{\partial\eta^{3}} + \hat{f}(\eta,q)\frac{\partial^{2}\hat{f}(\eta,q)}{\partial\eta^{2}} - \left(\frac{\partial\hat{f}(\eta,q)}{\partial\eta}\right)^{2} + \lambda\theta(\eta,q) - M^{2}\frac{\partial\hat{f}(\eta,q)}{\partial\eta},$$
(24)

$$\mathbf{N}_{\theta}[\hat{\theta}(\eta,q),\hat{f}(\eta,q)] = \frac{\partial^2 \hat{\theta}(\eta,q)}{\partial \eta^2} + \varepsilon \hat{\theta}(\eta,q) \frac{\partial^2 \hat{\theta}(\eta,q)}{\partial \eta^2} + \varepsilon \left(\frac{\partial \hat{\theta}(\eta,q)}{\partial \eta}\right)^2 - \Pr \alpha^* \hat{\theta}(\eta,q) \frac{\partial \hat{f}(\eta,q)}{\partial \eta} + \Pr \hat{f}(\eta,q) \frac{\partial \hat{\theta}(\eta,q)}{\partial \eta}, \quad (25)$$

where $q \in [0,1]$ is an embedding parameter, \hbar_f and \hbar_{θ} are the non-zero auxiliary parameters and \mathbf{N}_f and \mathbf{N}_{θ} the nonlinear operators. Note that for q = 0 and q = 1 we have:

$$\hat{f}(\eta;0) = f_0(\eta), \ \hat{\theta}(\eta,0) = \theta_0(\eta)$$
and
$$\hat{f}(\eta;1) = f(\eta), \ \hat{\theta}(\eta,1) = \theta(\eta),$$
(26)

and as q increases from 0 to 1 then $f(\eta,q)$ and $\theta(\eta,q)$ vary from $f_0(\eta)$, $\theta_0(\eta)$ to $f(\eta)$ and $\theta(\eta)$. Expanding f and θ in Taylor's series we obtain:

$$f(\eta, q) = f_0(\eta) + \sum_{m=1}^{\infty} f_m(\eta) q^m,$$
 (27)

$$\theta(\eta, q) = \theta_0(\eta) + \sum_{m=1}^{\infty} \theta_m(\eta) q^m, \qquad (28)$$

$$f_m(\eta) = \frac{1}{m!} \frac{\partial^m f(\eta; q)}{\partial \eta^m} \bigg|_{q=0},$$
(29)

$$\theta_m(\eta) = \frac{1}{m!} \frac{\partial^m \theta(\eta; q)}{\partial \eta^m} \bigg|_{q=0},$$

where the convergence of the above series strongly depends upon \hbar_f and \hbar_{θ} . Assuming that \hbar_f and \hbar_{θ} are selected properly so that (21) and (22) converge at q = 1, then:

$$f(\eta) = f_0(\eta) + \sum_{m=1}^{\infty} f_m(\eta),$$
 (30)

$$\theta(\eta) = \theta_0(\eta) + \sum_{m=1}^{\infty} \theta_m(\eta).$$
(31)

The problems at *m* th-order are:

$$L_f[f_m(\eta) - \chi_m f_{m-1}(\eta)] = h_f \mathbf{R}_f^m(\eta), \qquad (32)$$

$$L_{\theta}[\theta_m(\eta) - \chi_m \theta_{m-1}(\eta)] = h_{\theta} \mathbf{R}_{\theta}^m(\eta), \qquad (33)$$

$$f_m(0) = f'_m(0) = f'_m(\infty) = 0,$$
(34)

$$\theta_m(0) - \gamma \theta_m(0) = \theta_m(\infty) = 0,$$

$$\mathbf{R}_{f}^{m}(\eta) = f_{m-1}^{'''}(\eta) + \sum_{k=0}^{m-1} \left[f_{m-1-k} f_{k}^{''} - f_{m-1-k}^{'} f_{k}^{'''} \right] +\lambda \theta_{m-1}(\eta) - M^{2} f_{m-1}^{'}(\eta),$$
(35)

$$\mathbf{R}_{\theta}^{m}(\eta) = \theta_{m-1}^{''} + \varepsilon \sum_{k=0}^{m-1} \theta_{m-1-k} \theta_{k}^{''} + \varepsilon \sum_{k=0}^{m-1} \theta_{m-1-k} \theta_{k}^{'} - \Pr \alpha^{*} \sum_{k=0}^{m-1} \theta_{m-1-k} f_{k}^{'} + \Pr \sum_{k=0}^{m-1} \theta_{m-1-k} f_{k}^{'},$$
(36)

The general solutions are:

$$f_m(\eta) = f_m^*(\eta) + C_1 + C_2 e^{\eta} + C_3 e^{-\eta}, \qquad (37)$$

$$\theta_m(\eta) = \theta_m^*(\eta) + C_4 e^{\eta} + C_5 e^{-\eta},$$
(38)

where f_m^* and θ_m^* are our special solutions.

CONVERGENCE ANALYSIS

We know that expressions (30) and (31) contain the non-zero auxiliary parameters \hbar_f and \hbar_{θ} , which can adjust and control the convergence of the homotopy solutions. For admissible values of \hbar_f and \hbar_{θ} , the \hbar -curves have been potrayed for the 22nd-order of approximations. Figures 1 and 2 show that the ranges of admissible values of \hbar_f and \hbar_{θ} are $-1.6 \le \hbar_f \le -0.4$ and $-1.6 \le \hbar_{\theta} \le -0.6$. The convergence of series solutions is obtained in the whole region of η when $\hbar_f = \hbar_{\theta} = -1.0$. From Table 1, we observe that our series solutions converged from the 15th order of approximations. Therefore, the 15th order of approximation is enough for the convergent series solutions.



Figure 1: \hbar – curve for the function f

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Figure 2: \hbar – curve for the function θ

Table 1: Convergence of homotopy solutions for different orders of approximations when M = 0.6, $\lambda = 0.3$, $S = \alpha^* = 0.5$, $\gamma = \alpha = 1.0$, $\Pr = 0.7$, $\varepsilon = 0.2$ and $\hbar_f = \hbar_{\theta} = -1.0$.

Order of approximation	-f''(0)	<i>-θ'(0)</i>
1	1.35500	0.46042
5	1.34241	0.43457
10	1.34043	0.43293
15	1.34035	0.43286
20	1.34035	0.43286
30	1.34035	0.43286
40	1.34035	0.43286

DISCUSSION

The effects of emerging parameters on velocity and temperature are shown in this section. Hence Figures 3–20 are plotted for various values of the Hartman number M, buoyancy parameter λ , suction/ injection parameter S, positive constant α^* , Biot number γ , Prandtl number Pr and small parameter ε on velocity and temperature profiles $f'(\eta)$ and



Figure 3: Influence of *M* on $f'(\eta)$

 $\theta(\eta)$, respectively. Figures 3 and 4 indicate the velocity $f'(\eta)$ and temperature $\theta(\eta)$ for the Hartman number M. Figure 3 shows that an increase in Hartman number M decreases the fluid velocity and boundary layer thickness. This trend for the thermal boundary layer is quite opposite (see Figure 4). It is evident from Figure 5 that the velocity $f'(\eta)$ increases as the parameter λ increases, while the thermal boundary layer decreases (Figure 6). It is observed from Figures 7 and 8 that both the velocity and temperature profiles decrease with an increase in suction parameter S > 0. However, the opposite trend is observed for the injection parameter S < 0(see Figures 9 and 10). Figure 11 shows that the velocity field decreases upon increasing the parameter α^* . Figure 12 shows that α^* exerts a similar role on temperature and velocity in a qualitative sense. We can see from Figures 13 and 14 that, by increasing γ , both the velocity and temperature fields increase. By comparing Figures 15 and 16, we conclude that α gives the opposite results for $f'(\eta)$ and $\theta(\eta)$. Figures 17 and 18 describe the influence of Pr on $f'(\eta)$ and $\theta(\eta)$. Upon increasing Pr, both velocity and temperature decrease. The parameter γ has similar effects on velocity and temperature profiles (see Figures 19 and 20). Table 2 is constructed for the numerical values of the skin-friction coefficient and local Nusselt number. This table shows that, by increasing M, the values of the skin-friction coefficient increase, whereas the local Nusselt number decreases. However, increasing λ , we observed opposite results. An increase in S and λ^* causes an increase in both the skin-friction coefficient and the local Nusselt number.



Figure 4: Influence of *M* on $\theta(\eta)$

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Figure 11: Influence of α^* on $f'(\eta)$

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Table 2: Values of the skin-friction coefficient $\frac{1}{2}C_f \operatorname{Re}_x^{1/2}$ and the local Nusselt number $-Nu / \operatorname{Re}_x^{1/2}$ for different values of M, λ , S, α^* , γ , α , Pr and ε .

М	λ	S	α*	γ	α	Pr	3	$-\frac{1}{2}C_f \operatorname{Re}_x^{1/2}$	$-Nu / \operatorname{Re}_x^{1/2}$
0.0	0.3	0.5	0.5	1.0	1.0	0.7	0.2	1.31877	0.44115
0.5								1.46894	0.43525
1.0								1.57258	0.42083
0.5	0.0	0.5	0.5	1.0	1.0	0.7	0.2	1.44269	0.42559
	0.4							1.28068	0.43487
	1.0							1.07167	0.44455
0.5	0.3	0.0	0.5	1.0	1.0	0.7	0.2	1.03573	0.36543
		0.7						1.44901	0.45952
		1.5						2.04678	0.55625
0.5	0.3	0.5	0.0	1.0	1.0	0.7	0.2	1.32584	0.38455
			0.4					1.33775	0.42412
			0.8					1.34743	0.45686
0.5	0.3	0.5	0.5	0.1	1.0	0.7	0.2	1.42266	0.08893
				0.8				1.35059	0.39181
				2.0				1.31158	0.54579
0.5	0.3	0.5	0.5	1.0	0.0	0.7	0.2	0.21552	0.30248
					0.7			0.79535	0.40385
					1.5			2.37326	0.47078
0.5	0.3	0.5	0.5	1.0	1.0	0.2	0.2	1.23309	0.23051
						0.6		1.32677	0.40327
						1.0		1.36828	0.50358
0.5	0.3	0.5	0.5	1.0	1.0	0.7	0.0	1.34745	0.45485
							0.3	1.33675	0.42229
							0.8	1.31877	0.37428

CLOSING REMARKS

Mixed convection flow of a viscous fluid with variable thermal conductivity and convective boundary conditions is discussed. The main results are summed up as follows:

• The velocity field $f'(\eta)$ decreases upon increasing M and the temperature field $\theta(\eta)$ increases when M increases.

• Both $f'(\eta)$ and $\theta(\eta)$ increase when γ is increased.

• An increase in Pr leads to a decrease in the velocity and temperature profiles.

• The thermal boundary layer thickness decreases upon increasing Pr.

• α^* has similar effects on $f'(\eta)$ and $\theta(\eta)$ in a qualitative sense.

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